# 도클 ${ }^{\circledR}$ The Brand You Can Rely on 



## FBs - Series

## Programmable Logic Controller

- Cutting edge PLC
- State of the art technology
- Compact \& Powerful
- Extensive product range
- Reliable \& Durable



## Contents

Features ..... 01
System Configuration ..... 03
General Specifications ..... 05
Main Unit Specifications

- Basic Main Units (MA) ..... 09
- Basic Main Units (MA/MB) ..... 09
- Advanced Main Units (MC) ..... 09
- NC Positioning Main Units (MN) ..... 10
Right Side Expansion Module Specifications
- DIO Expansion Units ..... 10
- Power Supplies for Expansion Modules ..... 11
- DIO Expansion Modules ..... 11
- Thumbwheel Switch Module ..... 11
- 16/7 Segment LED Display Modules ..... 12
- AIO Modules ..... 12
- Temperature Measurement Modules ..... 12
- AI + Temperature Measurement Combo Modules ..... 13
- Voice Module ..... 13
- Load Cell Module ..... 13
- Potential Meter Module ..... 13
Left Side Expansion Module Specifications
- General Communication Boards/Modules ..... 13
- Ethernet Communication Boards/Modules ..... 14
- CANopen ${ }^{\circledR}$ Communication Board ..... 14
- ZigBee ${ }^{\text {TM }}$ Communication Modules ..... 14
- GSM Communication Module ..... 14
- General Purpose Communication Modules ..... 14
- AIO Boards ..... 15
-3-Axis Motion Control Module ..... 15
- Precision Load Cell Module ..... 15
- Handheld Programming Panel ..... 15
- Simple HMI ..... 15
Peripheral and Accessory Specifications
- RFID Card ..... 16
- PWMDA ..... 16
- Memory Pack ..... 16
- USB-RS232 Converter Cable ..... 16
- Communication Cable ..... 16
- High Density DIO Connection Cable ..... 16
- 16/7 Segment LED Display ..... 16
- Training Box ..... 17
Program Development Software WinProladder ..... 18
Instruction Sets ..... 19
Dimensions ..... 21
Model List ..... 23
"Quality" and "Functionality"


## Features

## SoC-FATEK's Core Technology

The FBs-PLC's design incorporates a "System on Chip" (SoC) developed in-house by Fatek Corporation. The BGA chip consists of over 120,000 gates which integrates powerful features such as a Central Processing Unit (CPU), Memory, Hardware Logic Solver (HLS), 5 high-speed communication ports, 4 sets of hardware high-speed counters/timers, 4 axes of high-speed pulse outputs for NC positioning control (with linear interpolation), 16 high-speed interrupts and captured inputs. The FBsPLC represents high functionality and reliability with exceptional value compared to other PLC's in its class.


## User friendly and powerful instruction sets

The FBs-PLC has more than 300 instructions which adopts a user friendly and readable multi-input/multi-output function structure. With this multi-input instruction structure the user can derive many types of functionality which other brands of PLC's may require the use of many instructions to achieve this. Also the operation result can be directly sent to internal or external outputs. To increase the program readability, the inputs or outputs for each function instruction have their own mnemonic symbol attached and the content of each operand is also displayed. For high-end applications, such as PLC networking (LINK), PID control and NC positioning etc, the FBs-PLC provides dedicated convenient instructions to assist in program development.

## Communication function (up to 5 ports including RS232, RS485, USB, Ethernet, CANopen ${ }^{\circledR}$ and GSM and ZigBee ${ }^{\text {TM }}$ wireless communication)

Via the five high-speed communication ports included in the SoC, the FBsPLC's communication capability is outstanding operating at a maximum speed of 921.6 Kbps . Communications can be achieved using ASCII code or the double-speed binary code. Along with FATEK's standard protocol, Modbus ASCII/RTU/TCP or user-definable protocols are also available. The FBs-PLC also provides the option of 8 different communication boards and 10 different communication modules for various types of communication applications. With their high speed and functionality the FBs-PLC has the greatest number of communication ports than any other PLC in its class. Each communication port comes standard with LED indicators for transmission (TX) and reception (RX) to enable the user to monitor the operation.

## Up to 4 sets of high-speed pulse width modulation (HSPWM) output

The SoC inside the FBs-PLC incorporates four sets of hardware high-speed pulse width modulation outputs with a maximum frequency of 184.32 KHz and 18.432 KHz with resolutions of $1 \%$ and $0.1 \%$, respectively. Different from the PWM function operated by software alone in other brands of PLC's, the hardware driven high-speed PWM in the FBs-PLC provides the user with easy control with high precision and stability.

## PLC \& NC Control in one and Dedicated NC Positioning Language

NC Position Control is incorporated into the SoC of the FBs-PLC which integrates PLC+NC control into one unit in order for resources sharing and reducing the need of data exchange. The NC position control adopts special positioning command language, which allows programming by mechanical or electrical units and the changing control of parameters during execution. One single unit has up to four axes outputs with a maximum frequency of $200 \mathrm{KHz}(\mathrm{MC})$ or $920 \mathrm{KHz}(\mathrm{MN})$ and equipped with multi-axis linear interpolation function. If combined with the four sets of built-in HHSC, it can achieve a fully closed loop positioning control!

## Integrated high-speed counters with counting frequency up to 920 KHz

The FBs-PLC includes up to 4 sets of hardware high-speed counters (HHSC) and 4 sets of software high-speed counters (SHSC). The highest counting frequency of a HHSC is $200 \mathrm{KHz}(\mathrm{MC})$ or $920 \mathrm{KHz}(\mathrm{MN})$. Each HHSC also has a clear and mask function. There are 8 counting modes including U/D, U/ $D \times 2, P / R, P / R \times 2, A / B, A / B \times 2, A / B \times 3$ and $A / B \times 4$ which makes the HHSC very powerful and efficient. For example, if the encoder, running at 200 pulses per revolution, adopts A/Bx4 mode the FBs-PLC can achieve the same result that 800 pulses per revolution encoder can provide. The counter is implemented in the hardware so as not to occupy CPU processing time. In addition, 4 sets of software high-speed counters (SHSC) has U/D, P/R, A/B 3 types of counting modes and the total counting frequency is 5 KHz .

## High-speed timers (HST)

The FBs-PLC is the only PLC in this class providing 0.1 mS high-speed timers (the FBs-PLC having one 16 -bit and 4 sets of 32 -bit HST). Currently, the fastest time base of high speed timers used in other brands of PLC's is 1 mS . By incorporating the interrupt function of the FBs-PLC the accuracy of 0.1 mS time base high-speed timer of FBs-PLC is further enhanced and can easily achieve more precise speed detection or can be used as a frequency meter. In most cases, expensive speed detection equipment can be replaced by the economical FBs-PLC.

## FATEK's Powerful Communication Features

The five communication ports in FBs-PLC can simultaneously connect to various intelligent peripherals with various interfaces such as USB, RS232, RS485, Ethernet, CANopen® and ZigBee ${ }^{\text {TM }}$. Apart from the FATEK and Modbus protocol or communication through the FATEK communication server, the user can also use the PLC's CLINK instruction for user-defined protocol to actively or passively establish connections with many intelligent peripherals.

## Open communication driver

The open communication protocol of the FBs-PLC is supported by all major brands of Supervisory Software (Scada) and Operator Terminals (HMI). Scada software such as Wonderware, Citec, Labview and LabLink! Operator terminals (HMI) such as Proface, Hitech/Beijer and Cermate can be directly connected with the FBs-PLC via serial and Ethernet interfaces. FATEK also provides FATEK DDE standard communication server or thirdparty OPC server for the user to easily connect the FBs-PLC to various control or supervisory systems. In addition, reputable companies such as National Instruments and KONTRON both sell FATEK OPC software package for users.

## Complete range of peripherals

In addition to over 200 models of main CPU units, the FBs-PLC also provides about 100 models of expansion I/O for selection. The expansion I/O modules include basic DI/O, AI/O and other communication modules, also include thumbwheel switch input module, 16/7 segment LED display module, 8 types (J, K, R, S, E, T, B, N) thermocouple, Pt100, Pt1000 RTD temperature measurement modules. There is also a new additions to the range including load cell module used in weighting, potential meter module used in measuring position, and a user-friendly voice module. The FBsPLC also provides a FBs-DAP or FBs- PEP simple HMI which can be linked together with a single RS485 bus. The FBs-DAP or FBs-PEP can be a simple Timer/Counter editor or it can also be used as a simple human machine interface through the function of user definable keys and message display. The FBs-DAP or FBs-PEP can be equipped with a wireless RFID sensing module and can be applied to such applications as entrance control, parking equipment and elevator control amongst others.

## User-friendly operating environment

"WinProladder" is the Windows-based ladder diagram programming software for the FBs-PLC. It provides a user-friendly operating environment with editing, monitoring and debugging functions which allows the user to become familiar with the operation of the software in a very short time. The powerful editing function of WinProladder, assisted with keyboard, mouse and on-line help (of ladder instructions and operating guide) greatly reduces programming development time. Features which can display the data registers directly in the ladder diagram and provide multiple status pages for monitoring gives the user the ability to monitor and debug easily.

## Up to 36 points of captured input

The SoC in the FBs-PLC has a captured input function, which captures and stores the external pulse of an input shorter than the scanning time of the CPU. Compared to PLC's in this class that either lack this capability or require highly sophisticated interrupt functions (which increase the CPU processing time), the FBs-PLC can handle this task easily as a general input, easily configured with high efficiency and no detriment the CPU scan time.

## Single unit with 16 points of high-speed interrupt

The FBs-PLC provides 16 points of external interrupts. The interrupt is edge driven and the user can define which edge triggers the interrupt and can be positive, negative or both edges. The interrupts can perform high speed, emergency processing which can withstand the time jilter caused by the delay and deviation of the scan time and can be used for precision high speed positioning, machine home and high speed RPM measurement applications.



## FATEK <br> General Specifications

## Environmental specifications

| Item |  |  | Specification | Note |
| :---: | :---: | :---: | :---: | :---: |
| Operating ambient temperature | Enclosure space | Minimum | $5^{\circ} \mathrm{C}$ | Permanent installation |
|  |  | Maximum | $40^{\circ} \mathrm{C}$ |  |
|  | Open space | Minimum | $5^{\circ} \mathrm{C}$ |  |
|  |  | Maximum | $55^{\circ} \mathrm{C}$ |  |
| Storage temperature |  |  | $-25 \sim 70^{\circ} \mathrm{C}$ |  |
| Relative humidity(non-condensing, RH-2) |  |  | 5~95\% |  |
| Pollution resistance |  |  | Degree II |  |
| Corrosion resistance |  |  | Base on IEC-68 standard |  |
| Altitude |  |  | s2000m |  |
| Vibration resistance | Fixed by DIN RAIL |  | $0.5 \mathrm{G}, 2$ hours for each direction of 3 axes |  |
|  | Fasten by screw |  | $2 \mathrm{G}, 2$ hours for each direction of 3 axes |  |
| Shock resistance |  |  | 10G, three times for each direction of 3 axes |  |
| Noise resistance |  |  | 1500 Vp-p, pulse width $1 \mu \mathrm{~S}$ |  |
| Withstand voltage |  |  | 1500VAC, 1 minute | L, N to any terminal |

## AC power supply specifications

| Item |  | $10 / 14$ points <br> main units | $20 / 24$ points <br> main units | $32 / 40$ points <br> main units |
| :---: | :---: | :---: | :---: | :---: |
| Input range | Voltage |  | $100 \sim 240 \mathrm{VAC},-15 \% /+10 \%$ |  |

## DC power supply specifications

| Specification | 10/14 points main units | 20/24 points main units | 32/40 points main units | 60 points main units |
| :---: | :---: | :---: | :---: | :---: |
| Input voltage | 12 or 24 VDC, $-15 \% /+20 \%$ |  |  |  |
| Max. power consumption (@ full built-in power supply) | 21W(SPW14-D12/D24) | 36W(SPW24-D12/D24) |  |  |
| Inrush current | 20A@12 or 24VDC |  |  |  |
| Allowable power momentary interruption time | $<2 \mathrm{mS}$ |  |  |  |
| Fuse rating | 3A(D12)/1.5A(D24),125V | 5A(D12)/2.5A(D24),125V |  |  |

Main unit specifications

* : Default, changable by user

| Item |  |  | Specification | Note |
| :---: | :---: | :---: | :---: | :---: |
| Execution speed |  |  | $0.33 \mathrm{uS} /$ Sequential instruction |  |
| Program capacity |  |  | 20K Words |  |
| Program memory |  |  | FLASH ROM or SRAM + Lithium battery for Back-up |  |
| Sequential instruction |  |  | 36 instructions |  |
| Function instruction |  |  | 326 instructions (126 kinds) | Include derivative instructions |
| Flow chart command (SFC) |  |  | 4 instructions |  |
| Communication Interface | Port 0 (RS232 or USB) |  | Communication speed 4.8k ~ 115.2Kbps (9.6Kbps)* |  |
|  | Port 1 ~ Port 4 (RS232, RS485 , Ethernet, CANopen or GSM) |  | Communication speed $4.8 \mathrm{k} \sim 921.6 \mathrm{Kbps}$ (9.6Kbps)* | Port1 ~ 4 provides FATEK or Modbus RTU/ASC II or user defined communication protocol |
|  | Maximum link stations |  | 254 |  |
| Digital (Bit status) | X | Input contact (DI) | X0~X255 (256) | Corresponding to external digital input |
|  | Y | Output relay (D0) | Y0~Y255 (256) | Corresponding to external digital output |
|  | TR | Temporary relay | TR0~TR39 (40) |  |


| Item |  |  |  |  |  | Spe | cation |  | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | M | Internal relay |  | Non-retentive | M0 ~ M799 (800)* |  |  |  | Can be configured as retentive type |
|  |  |  |  |  | M1400 ~ M1911 (512) |  |  |  |  |
|  |  |  |  | Retentive | M800 ~ M1399 (600)* |  |  |  | Can be configured as non-retentive type |
|  |  | Special relay |  |  | M1912 ~ M2001 (90) |  |  |  |  |
|  | S | Step relay |  | Non-retentive | S0 ~ S499 (500)* |  |  |  | S20 ~ S499 can be configured as retentive type |
|  |  |  |  | Retentive | S500 ~ S999 (500)* |  |  |  | Can be configured as non-retentive type |
|  | T | Timer "Time-Up" status contact |  |  | T0 ~ T255 (256) |  |  |  |  |
|  | C | Counter "Count-Up" status contact |  |  | C0 ~ C255 (256) |  |  |  |  |
|  | TMR | Timer current value register | 0.01S Time base |  | T0 ~ T49 (50)* |  |  |  | T0 ~ T255 numbers for each time base can be adjusted. |
|  |  |  | 0.1S Time base |  | T50 ~ T199 (150)* |  |  |  |  |
|  |  |  | 1S Time base |  | T200 ~ T255 (56)* |  |  |  |  |
|  | CTR | Counter current value register | 16-bit | Retentive | C0 ~ C139 (140)* |  |  |  | Can be configured as non-retentive type |
|  |  |  |  | Non-retentive | C140 ~ C199 (60)* |  |  |  | Can be configured as retentive type |
|  |  |  | 32-bit | Retentive | C200 ~ C239 (40)* |  |  |  | Can be configured as non-retentive type |
|  |  |  |  | Non-retentive | C240~C255 (16)* |  |  |  | Can be configured as retentive type |
|  | $\begin{aligned} & \text { HR } \\ & \text { DR } \end{aligned}$ | Retentive |  |  | R0 ~ R2999 (3000)* |  |  |  | Can be configured as non-retentive type |
|  |  |  |  |  | D0 ~ D3999 (4000) |  |  |  |  |
|  |  | Data register |  | Non-retentive | R3000 ~ R3839 (840)* |  |  |  | Can be configured as retentive type |
|  | $\begin{gathered} \text { HR } \\ \text { ROR } \end{gathered}$ |  |  | Retentive | R5000 ~ R8071 (3072)* |  |  |  | When not configured as ROR, it can serve normal register (for read/write) |
|  |  |  |  | Read only register | R5000 ~ R8071 can be set as ROR ~ default setting is (0)* |  |  |  | ROR is stored in special ROR area and not occupy program space |
|  |  |  |  | File register | F0 ~ F8191 (8192) |  |  |  | Save/retrieved via dedicated instruction |
|  | IR | Input register |  |  | R3840 ~ R3903 (64) |  |  |  | Corresponding to external numeric input |
|  | OR | Output register |  |  | R3904 ~ R3967 (64) |  |  |  | Corresponding to external numeric output |
|  | SR | Special system register |  |  | R3968 ~ R4167 (197), D4000 ~ D4095 (96) |  |  |  |  |
|  |  | 0.1 mS high-speed timer register |  |  | R4152 ~ R4154 (3) |  |  |  |  |
|  |  | High-speed counter register |  | rdware (4 sets) | DR4096 ~ DR4110 (4×4) |  |  |  |  |
|  |  |  |  | ftware (4 sets) | DR4112 ~ DR4126 (4x4) |  |  |  |  |
|  |  | Calendar Register |  |  | R4128 (sec) | R4129 (min) | R4130 (hour) | R4131 (day) | Optional for MA model |
|  |  |  |  |  | R4132 (month) | R4133 (year) | R4143 (week) |  |  |
|  | XR | Index register |  |  | V. Z (2), P0 ~ P9 (10) |  |  |  |  |
| Interrupt control |  | External interrupt control |  |  | 32 interrupts (16 points input positive/negative edge) |  |  |  |  |
|  |  | Internal interrupt control |  |  | 8 interrupts ( $1,2,3,4,5,10,50,100 \mathrm{mS}$ ) |  |  |  |  |
| 0.1 mS high speed timer(HST) |  |  |  |  | 1 (16-bit), 4 (32-bit, share with HHSC) |  |  |  |  |
|  | Hardware high-speed counter (HHSC) /32-bit |  |  | of channel | Up to 4 |  |  |  | - Total number of HHSC and SHSC is 8 <br> HHSC can be converted into 32 -bit/ 0.1 mS time base High-Speed Timer (HST) <br> - Half of maximum frequency while $A / B$ input |
|  |  |  |  | unting mode | 8 modes (U/D, | Dx2, P/R, P/Rx | , ${ }^{\text {, }} \mathrm{A} / \mathrm{Bx} 2, \mathrm{~A} / \mathrm{B}$ | A/Bx4) |  |
|  |  |  |  | unting frequency | Maximum is 200 (differential in | KHz (Single-en t) | nput) or 920 KH |  |  |
|  | Software high-speed counter (SHSC) /32-bit |  |  | of channel | Up to 4 |  |  |  |  |
|  |  |  |  | unting mode | 3 modes (U/D, | R, $A / B$ ) |  |  |  |
|  |  |  |  | unting frequency | Maximum sum | p to 5 KHz |  |  |  |
| NC position pulse out (HSPSO) |  | Number of axis |  |  | Up to 4 |  |  |  |  |
|  |  | Output frequency |  |  | Maximum is 200 KHz (Single-end output) or 920 KHz (differential output) |  |  |  | Half of the maximum while $A / B$ output |
|  |  | Pulse output mode |  |  | 3 modes (U/D, P/R, A/B) |  |  |  |  |
|  |  | Programming method |  |  | Dedicated position language |  |  |  |  |
|  |  | Interpolation |  |  | Maximum 4 axes linear interpolation |  |  |  |  |
| HSPWM output |  | Number of points |  |  | Up to 4 |  |  |  |  |
|  |  | Output frequency |  |  | $72 \mathrm{~Hz} \sim 18.432 \mathrm{KHz}$ (with $0.1 \%$ resolution) $720 \mathrm{~Hz} \sim 184.32 \mathrm{KHz}$ (with $1 \%$ resolution) |  |  |  |  |
| Captured input |  |  | Points |  | Maximum 36 points (All inputs in main unit are suitable this feature) |  |  |  |  |
|  |  |  | Minimum capturable Pulse width |  | $>10 \mu \mathrm{~S}$ (for ultra high speed / high speed input) |  |  |  |  |
|  |  |  | $>47 \mu \mathrm{~S}$ (for Medium speed input) |  |  |
|  |  |  | >470 $\mu \mathrm{S}$ (for Medium low speed input) |  |  |
| Digital filter |  |  |  |  | X0 ~ X15 |  | Adjustable freq | ency 14 KHz ~ | MHz |  | Chosen by frequency at high frequency |
|  |  |  |  |  | Adjustable tim | constant 0 ~ 1.5 | S/0~15mS ( un | 0.1mS/1mS ) | Chosen by time constant at low frequency |
|  |  |  |  | ~ X35 |  |  | Time constant | $\sim 15 \mathrm{mS}$ adjust | (unit: 1 ms ) |  |  |

## General Specifications

Digital Input (DI) Specifications

| Specification |  | 5VDC differential input | 24VDC single-end input |  |  |  | Notes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ultra high speed | High speed | Medium speed(HSC) | Medium Low speed (capture input) | Low speed |  |
| Maximum input frequency*/ accumulated time |  | 920KHz | 200 KHz | $\begin{gathered} 20 \mathrm{KHz}(\mathrm{HHSC}) \\ \text { Total } 5 \mathrm{KHz}(\mathrm{SHSC}) \end{gathered}$ | 0.47 mS | 4.7 mS | *: Half of maximum frequency while $A / B$ phase input |
| Input signal voltage |  | $5 \mathrm{VDC} \pm 10 \%$ | $24 \mathrm{VDC} \pm 10 \%$ |  |  |  |  |
| Threshold current | ON | $>11 \mathrm{~mA}$ | $>8 \mathrm{~mA}$ | $>4 \mathrm{~mA}$ |  | $>2.3 \mathrm{~mA}$ |  |
|  | OFF | $<2 \mathrm{~mA}$ |  | $<1.5 \mathrm{~mA}$ |  | $<0.9 \mathrm{~mA}$ |  |
| Maximum input current |  | 20 mA | 10.5 mA | 7.6 mA |  | 4.5 mA |  |
| Input indication |  | Displayed by LED: light when "ON" , dark when "OFF" |  |  |  |  |  |
| Isolation method |  | Photocouple isolation, 500VAC, 1 minute |  |  |  |  |  |
| SINK/SOURCE wiring |  | Independent wiring | Via variation of internal common terminal $S / S$ and external common wiring |  |  |  |  |
| Noise filtering methods |  | $\begin{aligned} & \text { DHF }(0 \sim 15 \mathrm{mS}) \\ & + \text { AHF }(0.47 \mu \mathrm{~S}) \end{aligned}$ |  | $\begin{aligned} & \text { DHF ( } 0 \sim 15 \mathrm{mS} \text { ) } \\ & \text { +AHF }(4.7 \mu \mathrm{~S}) \end{aligned}$ | $\begin{aligned} & \text { DHF ( } 0 \sim 15 \mathrm{mS}) \\ & + \text { AHF }(0.47 \mathrm{mS}) \end{aligned}$ | AHF ( 4.7 mS ) | DHF: Digital Hardware Filter AHF: Analog Hardware Filter |

Wiring of 5VDC differential input (with frequency up to 920 KHz , for high speed or high noise environments)


Wiring of 5VDC differential input to 5VDC single-end
SINK/SOURCE input (Max. 200KHz)


Wiring of 24VDC single-end SINK input


Wiring of 5VDC differential input to 24VDC single-end
SINK /SOURCE input (Max. 200KHz)


Wiring of 24VDC single-end SOURCE input


# General Specifications 

Digital Output (DO) Specifications

| Specification Item |  | Differential output | Single-end transistor output |  |  | Single-end relay output |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ultra high speed | High speed | Medium speed | Low speed |  |
| Maximum output frequency* |  | 920 KHz | 200 KHz | 20 KHz | - | - |
| Working voltage |  | 5VDC $\pm 10 \%$ | 5~30 VDC |  |  | <250VAC/30VDC |
| Maximum load current | Resistive | 50 mA | 0.5A | 0.5A | 0.5A/0.1A (24YT/J) | 2A/single, 4A/common |
|  | Inductive |  |  |  |  | $80 \mathrm{VA}(\mathrm{AC}) / 24 \mathrm{VA}(\mathrm{DC})$ |
| Maximum voltage drop/ conducting resistance |  | - | 0.6 V | 2.2 V | 2.2 V | 0.06 V (initial) |
| Minimum load |  | - | - |  |  | $2 \mathrm{~mA} / \mathrm{DC}$ power |
| Leakage current |  | - | $<0.1 \mathrm{~mA} / 30 \mathrm{VDC}$ |  |  | - |
| Maximum output delay time | ON $\rightarrow$ OFF | 200ns | $2 \mu \mathrm{~S}$ | 154S |  | 10 mS |
|  | OFF $\rightarrow$ ON |  |  | 30 S |  |  |
| Output status indication |  | Displayed by LED: Light when "ON", dark when "OFF" |  |  |  |  |
| Over current protection |  | N/A |  |  |  |  |
| Isolation type |  | Photocouple isolation, 500VAC, 1 minute |  |  |  | Electromagnetic isolation 1500VAC, 1 minute |
| SINK/SOURCE output type |  | Independent dual terminals for arbitrary connection | Choose SINK/SOURCE by models and non-exchangeable |  |  | Can be arbitrarily set to SINK/SOURCE output |

*: Half of the maximum frequency while $A / B$ phase output


Wiring of transistor single-end SINK output


Wiring of transistor single-end SOURCE output


Wiring of relay single-end output


Fatek Main Unit Specifications

| Basic Main Units (MA) |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specification Model |  |  | FBs-10MAR | FBs-10MAT/J | FBs-14MAR | FBs-14MAT/J | FBs-20MAR | FBs-20MAT/J | FBs-24MAR | FBs-24MAT/J |
| 믗 | 24VDC | $\begin{aligned} & \text { Medium speed } \\ & (20 \mathrm{KHz}) \\ & \hline \end{aligned}$ | 4 points |  |  |  | 6 points |  | 8 points |  |
| 言 |  | Medium speed (Total 5KHz) | 2 points |  | 4 points |  | 6 points |  |  |  |
| 믄읓은듣 |  | Relay | 4 points | - | 6 points | - | 8 points | - | 10 points | - |
|  | Transistor | Medium speed (20KHz) | - | 4 points | - | 6 points | - | 8 points | - | 8 points |
|  |  | Low speed | - | - | - | - | - | - | - | 2 points |
| Communication Port |  | Built-in | 1 port (Port0, USB or RS232) |  |  |  |  |  |  |  |
|  |  | Expandable | 2 ports (Port1~2, RS485 or RS232 or Ethernet) |  |  |  |  |  |  |  |
| Calendar |  |  | optional |  |  |  |  |  |  |  |
| Built-in power supply |  |  | SPW14-AC/D12/D24 |  |  |  | SPW24-AC/D12/D24 |  |  |  |
| Wiring mechanism |  |  | 7.62 mm fixed terminal block |  |  |  |  |  |  |  |
| Dimension |  |  | Figure 2 |  |  |  | Figure 1 |  |  |  |

## Basic Main Units (MA/MB)



Advanced Main Units (MC)

| Specification |  | Mode |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { 믈 } \\ & \underline{\overline{\#}} \\ & \text { 言 } \\ & \text {. } \end{aligned}$ | 24VDC | High speed (200KHz) |
|  |  | Medium speed (20KHz) |
|  |  | Medium speed (Total 5KHz) |
| 믈흥응듣 | Relay |  |
|  | Transistor | High speed (200KHz) |
|  |  | Medium speed (20KHz) |
|  |  | Low speed |
| Communication Port |  | Built-in |
|  |  | Expandable |
| Calendar |  |  |
| Built-in power supply |  |  |
| Wiring mechanism |  |  |
| Dimension |  |  |


| Advanced Main Units (MC) |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specification Model |  |  | FBs-32MCR | FBs-32MCT/J | FBs-40MCR | FBs-40MCT/J | FBs-60MCR | FBs-60MCT/J |
|  | 24VDC | High speed (200KHz) | 6 points |  |  |  | 8 points |  |
|  |  | Medium speed (20KHz) | 2 points |  |  |  | - |  |
|  |  | Medium speed (Total 5KHz) | 8 points |  |  |  |  |  |
|  |  | $\begin{gathered} \text { Medium Iow } \\ \text { speed }(0.47 \mathrm{~ms}) \end{gathered}$ | 4 points |  | 8 points |  | 20 points |  |
| Relay |  |  | 12 points | - | 16 points | - | 24 points | - |
|  | Transistor | $\begin{gathered} \text { High speed } \\ (200 \mathrm{KHz}) \\ \hline \end{gathered}$ | - | 6 points | - | 6 points | - | 8 points |
|  |  | $\begin{gathered} \text { Medium speed } \\ (20 \mathrm{KHz}) \\ \hline \end{gathered}$ | - | 2 points | - | 2 points | - | - |
|  |  | Low speed | - | 4 points | - | 8 points | - | 16 points |
| Communication Port |  | Built-in | 1 port (Port0, USB or RS232) |  |  |  |  |  |
|  |  | Expandable | 4 ports (Port1~4, RS485 or RS232 or Ethernet or GSM or ZigBee) |  |  |  |  |  |
| Calendar |  |  | Built-in |  |  |  |  |  |
| Built-in power supply |  |  | SPW24-AC/D12/D24 |  |  |  |  |  |
| Wiring mechanism |  |  | 7.62 mm detachable terminal block |  |  |  |  |  |
| Dimension |  |  | Figure 1 |  |  |  |  |  |

NC Positioning Main Units (MN)

| Specification |  | Model |
| :---: | :---: | :---: |
|  | 5VDC <br> Differential | Ultra high speed (920KHz) |
|  | 24VDC | High speed (200KHz) |
|  |  | Medium speed (Total 5KHz) |
|  |  | Low speed |
| 믗읗은듣 | Relay |  |
|  | 5VDC <br> Differential | Ultra high speed $\text { ( } 920 \mathrm{KHz} \text { ) }$ |
|  | Transistor | High speed (200KHz) |
|  |  | Low speed |
| Communication Port |  | Built-in |
|  |  | Expandable |
| Calendar |  |  |
| Built-in power supply |  |  |
| Wiring mechanism |  |  |
| Dimension |  |  |

为
FBs-20MNR


FBs-20MNT/J


FBs-32MNR


FBs-32MNT/J




## Right Side Expansion Module Specifications



## Right Side Expansion Module Specifications



| DIO Expansion Modules |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specific | ation | Model | FBs-8XYR | FBs-8XYT/J | FBs-8X | FBs-8YR | FBs-8YT/J | FBs-16XYR | FBs-16XYT/J | FBs-20X |
| Digital Input | 24VDC | Low Speed | 4 points |  | 8 points | - | - | 8 points |  | 20 points |
| Digital Output | Relay |  | 4 points | - | - | 8 points | - | 8 points | - | - |
|  | Transistor | Low Speed | - | 4 points | - | - | 8 points | - | 8 points | - |
| Wiring mechanism |  |  | 7.62 mm fixed terminal block |  |  |  |  |  |  |  |
| Dimension |  |  | Figure 4 |  |  |  |  | Figure 3 |  |  |


| (Continu |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specification |  |  | FBs-16YR | FBs-16YT/J | FBs-24X | FBs-24YT/J | FBs-24XYR | FBs-24XYT/J | FBs-40XYR |
| Digital Input | 24VDC | Low Speed | - | - | 24 points | - |  |  | 24 points |
| Digital Output | Relay |  | 16 points | - | - | - | 10 points | - | 16 points |
|  | High density low speed |  | - | - | - | 24 points | - | - | - |
|  | Transistor | Low Speed | - | 16 points | - | - | - | 10 points | - |
| Wiring mechanism |  |  | 7.62 mm fixed terminal block |  | 30 pins header with latch |  | 7.62 mm fixed terminal block |  |  |
| Dimension |  |  | Figure 3 |  | Figure 6 |  | Figure 1 |  |  |


| (Continue) |  |  |  |  |  | Thumbwheel Switch Module |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specification Model |  |  | FBs-40XYT/J | FBs-60XYR | FBs-60XYT/J | Specification Model | FBs-32DGI |
| Digital Input | 24VDC | $\begin{aligned} & \text { Low } \\ & \text { Speed } \end{aligned}$ | 24 points | 36 points |  | Refresh time for input | 10 mS max. |
| Digital Output | Relay |  | - | 24 points | - | Input capability | points) |
|  | Transistor | $\begin{aligned} & \text { Low } \\ & \text { Speed } \end{aligned}$ | 16 points | - | 24 points | Input method | 1/8 duty multiplexing input scan |
| Wiring mechanism |  |  | 7.62 mm fixed terminal block |  |  | Wiring mechanism | 30 pins header with latch |
| Dimension |  |  | Figure 1 |  |  | Dimension | Figure 6 |

## Right Side Expansion Module Specifications

## 16/7 Segment LED Display Modules

| Specification | Model |
| :---: | :---: |
| $\begin{array}{c}\text { Display } \\ \text { mode }\end{array}$ | Decoding display |
|  | Non-decoding display |
| Display number of character |  |


| Display number of character (points) |  |  | 1 channel, 7 segment 8 words / 16 segment 4 words or 64 points individual LED | 2 channels, 7 segment 16 words/ 16 segment 8 words or 128 points individual LED |
| :---: | :---: | :---: | :---: | :---: |
| Refresh time for display |  |  | 10 mS max. |  |
|  | Drivin | gin current | 40 mA / segment |  |
|  | Display | yy method | 1~8 duty multiplexing display |  |
|  | Driving | Low voltage | 5VDC (can be 10\% up) |  |
|  | voltage | High voltage | $7.5 \mathrm{~V}, 10 \mathrm{~V}, 12.5 \mathrm{~V}$ selectable (can be $10 \%$ up) |  |
|  | Fine tu | ne of voltage drop | $0.6 \mathrm{~V}, 1.2 \mathrm{~V}, 1.8 \mathrm{~V}$ selectable |  |
| Over voltage driving indication |  |  | Each channel has individual Over Voltage (O.V.) driving LED indication (should be under Test Mode) |  |
| Isolation method |  |  | Transformer (power) and photocouple (signal) isolation, 500VAC, 1 minute |  |
| Power consumption |  |  | $24 \mathrm{VDC}-15 \% /+20 \%$, static consumption is 2W max., dynamic current is increased according to display |  |
| Wiring mechanism |  |  | 16 pins flat cable, 2.54 mm header connector |  |
| Dimension |  |  | Figure 4 |  |



| Temperature Measurement Modules |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Specification Model | FBs-2TC | FBs-6TC | FBs-16TC | FBs-6RTD | FBs-16RTD | FBs-6NTC |
| Number of input points | 2 points | 6 points | 16 points | 6 points | 16 points | 6 points |
| Sensor type and temperature measurement range | Thermocouple Sensor:$\begin{gathered} \mathrm{J}\left(-200 \sim 1200^{\circ} \mathrm{C}\right) \mathrm{E}\left(-190 \sim 1000^{\circ} \mathrm{C}\right) \\ \mathrm{K}\left(-190 \sim 1300^{\circ} \mathrm{C}\right) \mathrm{T}\left(-190 \sim 380^{\circ} \mathrm{C}\right) \\ \mathrm{R}\left(0 \sim 1800^{\circ} \mathrm{C}\right) \mathrm{B}\left(350 \sim 1800^{\circ} \mathrm{C}\right) \\ \mathrm{S}\left(0 \sim 1700^{\circ} \mathrm{C}\right) \mathrm{N}\left(-200 \sim 1000^{\circ} \mathrm{C}\right) \end{gathered}$ |  |  | $\begin{gathered} \text { 3-wire RTD sensor (JIS or DIN) } \\ \text { Pt100 }\left(-200 \sim 850^{\circ} \mathrm{C}\right) \\ \operatorname{Pt} 1000\left(-200 \sim 600^{\circ} \mathrm{C}\right) \end{gathered}$ |  | NTC sensor $10 \mathrm{~K} \Omega$ at $25^{\circ} \mathrm{C}, \mathrm{B}$ optional -20~100 ${ }^{\circ} \mathrm{C}$ |
| Temperature compensation | Built-in cold junction compensation |  |  | - | - | - |
| Resolution | $0.1{ }^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Temperature refresh time | 1 or 2 seconds | 2 or 4 seconds | 3 or 6 seconds | 1 or 2 seconds | 2 or 4 seconds | 2 or 4 seconds |
| Overall Precision | $\pm\left(1 \%+1^{\circ} \mathrm{C}\right)$ |  |  | $\pm 1 \%$ |  | $\pm 1 \%$ of full scale at $25^{\circ} \mathrm{C}$ |
| Isolation method | Transformer(power) and photocouple(signal) isolation, 500VAC, 1 minute, isolation between each channel |  |  | Transformer(power) and photocouple(signal) isolation, 500VAC, 1 minute, no isolation between each channel |  |  |
| Power consumption | 24VDC -15\%/+20\%, 2W max. |  |  |  |  |  |
| Wiring mechanism | 3.81 mm european terminal block |  | 7.62 mm fixed terminal block |  |  |  |
| Dimension | Figure 4 |  | Figure 1 | Figure 4 | Figure 1 | Figure 4 |

# Right/Left Side Expansion Module Specifications 

| Al+Temperature Measurement Combo Modules |  |  |
| :---: | :---: | :---: |
| Specification Model | FBs-2A4TC | FBs-2A4RTD |
| Analog input (AI) points | 2 point |  |
| Temperature measurement input points | 4 points (thermocouple) | 4 points (RTD) |
| Analog input specification | Same as FBs-6AD | Same as FBs-6AD |
| Temperature input specification | Same as FBs-6TC | Same as FBs-6RTD |
| Power consumption | 24VDC-15\%/+20\%, 2W max. |  |
| Wiring mechanism | 7.62 mm fixed terminal block |  |
| Dimension | Figure 4 |  |


| Load Cell Module |  |
| :---: | :---: |
| Specification Model | FBs-1LC |
| Number of channel | 1 channel |
| Resolution | 16-bit (including sign bit) |
| Occupied I/O points | 1 IR (input register) and 8 points DO |
| Sampling frequency | 5/10/20/25/60/120/240/480 Hz optional |
| Non-linearity degree | $0.01 \%$ full scale @ $25{ }^{\circ} \mathrm{C}$ |
| Zero drift | $0.2 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ |
| Gain drift | $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Excitation voltage | 5 V , maximum load is $250 \Omega$ |
| Level of sensitivity | $2 \mathrm{mV} / \mathrm{V}, 5 \mathrm{mV} / \mathrm{V}, 10 \mathrm{mV} / \mathrm{V}, 20 \mathrm{mV} / \mathrm{V}$ |
| Filters | Moving averages |
| Isolation method | Transformer (power) and photocouple (signal) isolation, 500VAC, 1 minute |
| Power consumption | 24VDC, -15\%/+20\%, 2W |
| Wiring mechanism | 7.62 mm fixed terminal block |
| Dimension | Figure 4 |

## Left Side Expansion Module Specifications

Voice Module

| Specification Model |  | FBs-VOM |
| :---: | :---: | :---: |
| Number of recorded messages |  | 245 messages |
| Sound storage device |  | Internal memory or external SD memory card |
| Maximum sound storage capacity | Internal memory | 1 MB , can play up to 2 minutes of sound recordings. |
|  | External SD memory card | Maximum 4 GB memory card, up to 8000 minutes of sound recordings can be played. |
| Applicable sound encoding format |  | Mono 8 bit 8 KHz sample |
| Signal output |  | Dual output 8Vp-p, $4 \Omega$ load 2W output |
| Sound input method |  | Computer editing, SD memory card |
| Sound playback control |  | PLC control or manual sequencing (test play) |
| Volume control |  | PLC control, total of 10 volumes |
| I/O points occupy |  | 8 points DI and 8 points DO |
| Status display |  | 3 LEDs |
| Power consumption |  | Internal 5V, 500mA (@2W output) |
| Dimension |  | Figure 4 |

Potential Meter Module


| Specification Model | FBs-4PT |
| :---: | :---: |
| Number of channel | 4 channels |
| Resolution | 14 or 12 bits |
| Occupied I/O points | 4 IR (input registers) and 1 unused OR (output register) |
| Conversion time | Conversion once for each scan |
| Accuracy | $\pm 1 \%$ |
| Potential meter impedance | $1 \mathrm{~K} \sim 10 \mathrm{~K} \Omega$ |
| Voltage Input Range | 0~10V |
| Potential meter voltage | 10V |
| Filters | Moving averages |
| Isolation method | Transformer (power) and photocouple (signal) isolation, 500VAC, 1 minute |
| Power consumption | 24VDC, -15\%/+20\%, 2W |
| Wiring mechanism | 7.62 mm fixed terminal block |
| Dimension | Figure 4 |


| (Continue) |  |  |  |
| :---: | :---: | :---: | :---: |
| Specification Model | FBs-CM22 | FBs-CM55 | FBs-CM25 |
| RS232 Port | 2 ports (Port3, Port4) | - | 1 port (Port3) |
| RS485 Port | - | 2 ports (Port3, Port4) | 1 port (Port4) |
| Indicators | Each Port has its own TX, RX LED indicators |  |  |
| Wiring mechanism | DB9F | 3 pins spring terminal | DB9F, 3 pins spring terminal |
| Installation position | Figure 5 |  |  |

## Left Side Expansion Module Specifications



| CANopen ${ }^{\text {® }}$ |
| :---: | :---: |
| Communication Board |
| Specification Model |$\quad$| CAN 2.0A CANopen |
| :---: |
| Communication <br> standard |
| Network topology |

ZigBee ${ }^{\text {TM }}$
Communication Modules

| Specification Model | FBs-CMZB |
| :---: | :---: | :---: |
| Standards | Based on IEEE 802.15.4 and ZigBee ${ }^{\text {TM }}$ standard |



FBs-CMGSM

| Specification Model | FBs-CMGSM |
| :---: | :---: |
| Function | SMS, GPRS, and dial up data <br> transfer (CSD), and etc |
| Frequencies | $850 / 900 / 1800 / 1900 \mathrm{MHz}$ |
| RF power | 2 W |
| Communication <br> interface | Port3 |
| Dimension | Figure 5 |

General Purpose Communication Modules

| Specification Model | FBs-CM25C | FBs-CM5R | FBs-CM5H |  |
| :---: | :---: | :---: | :---: | :---: |
| Function | General purpose RS232 <br> to RS485 bi-directional <br> signal converter | General purpose RS485 <br> repeater | General purpose 1 to 3 <br> RS485 HUB |  |
| Indicators | Each port has its own independent TX, RX LED indicator |  |  |  |
| External power | 24VDC, -15\%/+20\% |  |  |  |
| Wiring mechanism | DB9F, 3.81mm European <br> terminal block | 3 pins spring terminal <br> block | 7.62mm fixed terminal <br> block |  |
| Dimension | Figure 5 |  |  | Figure 4 |

## Left Side Expansion Module Specifications

| Model |  |  |  |
| :---: | :---: | :---: | :---: |
| Specification |  | FBs-B2DA |  |
| Input point | - | 4 points | FBs-B2A1D |
| Output point | 2 points | - | 2 points |
| Input / Output value |  | $0 \sim 1630$ (14-bit representation, valid 12-bit) |  |
| Input / Output polar |  | Unipolar |  |
| Input / Output counting range |  | $0 \sim 10 \mathrm{~V}$ |  |
| Conversion time |  | Conversion once for each scan |  |
| Accuracy |  | $\pm 1 \%$ |  |
| Isolation method |  | Non-isolation |  |
| Wiring mechanism |  | 3.81 mm European terminal block |  |
| Installation position |  | The expansion slot of main unit |  |

## 3-Axis Motion Control Module

| Sodel |  |
| :---: | :---: |
| Specification |  |
| Number of DIO points | 14 points (8 inputs/6 outputs) |
| Program capacity | 16 M Bytes |
| Data Register | 20K Words |
| High speed pulse Input | 200KHz X,Y,Z 3-Axis A/B differential signal input |
| High speed pulse Output | $500 \mathrm{KHz} \mathrm{X,Y,Z} \mathrm{3-Axis} \mathrm{A/B} \mathrm{differential} \mathrm{signal} \mathrm{output}$ |
| Manual input | A/B differential signal input |
| Communication port | RS485 x1, Ethernet x1 |
| Built-in power supply | SPW24-AC/D12/D24 |
| Wiring mechanism | 7.62 mm detachable terminal block |
| Dimension | Figure 1 |


| Precision Load Cell | dule |
| :---: | :---: |
| Specification Model | FBs-1HLC |
| Number of channels | 1 channel |
| Resolution | $0.10 \mu \mathrm{~V} / 1 \mathrm{D}$ (24-bit AD) |
| Filters | Digital filter, sampling rate 6.25~120Hz |
| Measurement range | -1~39mV |
| Sensor voltage | $5 \mathrm{VDC} \pm 5 \%$ |
| No. of sensor connections | $350 \Omega$ sensor $\times 8$ |
| Isolation Method | Transformer (power) and photocouple (signal) isolation, 500VAC, 1 minute |
| Power consumption | 24VDC, $-15 \% /+20 \%$, 2W |
| Wiring mechanism | 7.62 mm fixed terminal block |
| Dimension | Figure 4 |

## Precision Load Cell Module

| Specification Model | FP-08 |
| :---: | :---: |
| Main function | Program editor (Mnemonic language), status <br> monitoring, parameters setup, program/parameter <br> import and recording, etc. |
| Max. of power <br> consumption | $5 \mathrm{~V} / 100 \mathrm{~mA}$ |
| Keyboard | 48 silicon rubber keys |
| Display | Two rows 16 characters, dot matrix LCD display, with |
| LED backlight |  |$|$| Recording device | FBs-PACK read/write |
| :---: | :---: |
| Communication port | RS232 serial communication port |
| Connectors | DB9F, Mini-DIN |
| Dimension | Figure 7 |

##  <br> Handheld Programming Panel



Simple HMI



| General features |  |
| :---: | :--- |
| Special features | Alarm, infor |
| Card access features (RFID card) |  |
| Dimension (Installation position) |  |

* The PLC main unit must be of calendar built-in type


# Peripheral and Accessory Specifications 

| RFID Card |  | PWMDA |  |
| :---: | :---: | :---: | :---: |
|  | CARD-H | Specification Model | PWMDA |
| Operated frequency | 13.56 MHz | Output range | 0~10V |
| Memory | 64-bit with Cyclic Redundancy Check (CRC) on data | Output value | 0~1000 |
| Working temperature | -25~50 (ISO7810) | Resolution | 10 mV (10V/1000) |
| Power source | Powered by RF | Output impedance | $1 \mathrm{~K} \Omega$ |
| Receivable distance | $6 \sim 12 \mathrm{~cm}$ | Min. load ( $\geq 10 \mathrm{~V}$ ) | $5.2 \mathrm{~K} \Omega$ |
| Writable times | At least 10000 times | D/A conversion time | $<50 \mathrm{mS}$ |


| Memory Pack | 1 | USB-RS232 Converter Cable |  |
| :---: | :---: | :---: | :---: |
| Specification Model | FBs-PACK | Specification Model | FBs-U2C-MD-180 |
| Memory | 1M bits FLASH ROM | Features | Standard USB AM connector to RS232 MD4M connector (used in standard PC USB to FBs main unit Port 0 RS232), length 180 cm |
| Memory capacity | 20K Words program + 20K Words data |  |  |
| Write protection | DIP switch ON/OFF protection |  |  |

## Communication Cable



| Communication Cable |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Specification Model | FBs-232P0-9F-150 | FBs-232P0-9M-400 | FBs-232P0-MD-200 | FBs-232P0-MDR-200 |
| Features | Dedicated communication cable for FBs main unit Port 0 (RS232) to DB9F connector, length 150 cm | Dedicated communication cable for FBs main unit Port 0 (RS232) to DB9M connector, length 400 cm | Dedicated communication cable for FBs main unit Port 0 (RS232) to FBs-PEP/PEPR Mini-DIN male connector, length 200 cm | Dedicated communication cable for FBs main unit port 0 (RS232) to FBs-PEP/PEPR 90 Mini-DIN male connector, length 200 cm |

High Density DIO Connection Cable

| Specification Model | HD30-22AWG-200 |
| :---: | :---: |
| Features | 22 AWG I/O cable with 30 pins Socket, length <br> 200 (for FBs-24X, 24YT/J and 32DGI) |
|  |  |

16/7 Segment LED Display



|  | DBAN.8-nR | DBAN2.3-nR |
| :---: | :---: | :---: |
| Features | 0.8" 4-digit 16-segment LED <br> display,, n means R(Red) <br> 16-segment LED characters <br> display installed, can be 1~4 | 2.3" 4-digit 16-segment <br> LED display, n means R(Red) <br> 16-segment LED characters <br> display installed, can be 1~4 |

Training Box


## Features:

- It contains the basic items required by PLC digital I/O training, such as the FBs-24MCT advanced main unit, the FBs-CM25E Ethernet module, digital input socket, simulated switches, and digital output socket.
- The built-in RS232, RS485 and the Ethernet three ports (can be expanded to five with communication boards) not only enable the teacher's computer to connect with the training kits of all students to conduct networking on-line teaching such as loading, monitoring, modifying, and storing, but also can be used in advanced course such as computer connection, intelligent
 ASCII peripherals as well.
- A special designed software "WinProladder teaching assistant" can let instructor download or upload ladder program to or from the PLC of the whole class or individual through computer.
- PLC output is isolated by the Relay with socket and fuse and then output to terminal. These isolations can prevent PLC from damaging caused by incorrect wiring and easy for repair and replacement.


## Program Development Software

## General Features

- Windows based application program following the standard conventions of a windows environment for ease of learning and operation regardless of whether the user is a beginner or frequent user.
- Application environment for project development is via a hierarchical tree. All the elements of the project can be activated by directly clicking the mouse button on the tree object providing comprehensive access and views of the working project.
- Easy entry methods which incorporate both the keyboard and mouse as entry devices. No matter whether on site or in an office environment the software can be operated with ease and efficiency.
- Provides various types of connections to the PLC via a PC. Connections include serial, USB, Ethernet / Internet and Modem. For every different connection WinProladder provides a session name to associate the setting of the communication parameters, such as port no., baud rate, IP address, phone number, etc.

- On-Line, Run-Time program editing
- Program testing
- Program comments
- Project oriented program
- Ladder program editing screen
- Status monitor and control
- Mnemonic ladder instruction display window
- Ladder diagram with comments
- Element comment editing
- Off-Line Simulation



## Instruction Sets

## Sequential instructions

| Instruction | Operand | Ladder symbol | Function |
| :---: | :---: | :---: | :---: |
| ORG | $\begin{gathered} \mathrm{X}, \mathrm{Y}, \mathrm{M}, \\ \mathrm{~S}, \mathrm{~T}, \mathrm{C} \end{gathered}$ | $\bullet \longmapsto$ | Network starts by an A contact |
| ORG NOT |  | $\bullet / \longmapsto$ | Network starts by a B contact |
| ORG TU |  | $\bullet$ - $\uparrow$ - | Network starts by a TU contact |
| ORG TD |  | - $\backslash \downarrow$ - | Network starts by a TD contact |
| ORG OPEN |  | - | Network starts by an open contact |
| ORG SHORT |  | $\bullet \quad$ - | Network starts by a short contact |
| LD | $\begin{gathered} \mathrm{X}, \mathrm{Y}, \mathrm{M}, \\ \mathrm{~S}, \mathrm{~T}, \mathrm{C} \end{gathered}$ | ¢ - • | Branch line starts by an A contact |
| LD NOT |  | $\downarrow / \longmapsto$ | Branch line starts by a $B$ contact |
| LDTU |  | $\downarrow$ ¢ | Branch line starts by a TU contact |
| LDTD |  | $\downarrow \downarrow$ - | Branch line starts by a TD contact |
| LD OPEN |  | ¢ - | Branch line starts by an open contact |
| LD SHORT |  | $\downarrow$ - | Branch line starts by a short contact |
| AND | $\begin{gathered} \mathrm{X}, \mathrm{Y}, \mathrm{M}, \\ \mathrm{~S}, \mathrm{~T}, \mathrm{C} \end{gathered}$ | $\rightarrow \longmapsto$ | Serial connect with an A contact |
| AND NOT |  | $\rightarrow-1 /$ | Serial connect with a B contact |
| AND TU |  | $\rightarrow-\uparrow \longmapsto$ | Serial connect with a TU contact |
| AND TD |  | $\cdots \downarrow \mid$ • | Serial connect with a TD contact |
| AND OPEN |  | $\rightarrow$ - | Serial connect with an open contact |
| AND SHORT |  | $\rightarrow \quad$ | Serial connect with a short contact |



## Step ladder instructions (SFC)

| Instruction | Operand | Ladder symbol | Function |
| :---: | :---: | :---: | :--- |
| STP | Snnn | STP- | Define STEP program |
| STPEND |  | $-\boxed{\text { STPEND }}$ | STEP program end |


| Instruction | Operand | Ladder symbol | Function |
| :---: | :---: | :---: | :--- |
| TO | Snnn | - TO | STEP divergence |
|  |  | FROM | STEP convergence |

## Function instructions

| Category | NO. | Instruction | Derivative | Function |
| :---: | :---: | :---: | :---: | :---: |
| Timer |  | Tnnn |  | General timer instruction (T0 ~ T255) |
| Counter |  | Cnnn |  | General counter instruction (C0 ~ C255) |
|  | 7 | UDCTR | D | 16 or 32-bit up/down counter |
| Setting / Resetting |  | SET | DP | Set all bits of register or a discrete point to 1 |
|  |  | RST | DP | Clear all bits of register or a discrete point to 0 |
|  | 114 | Z-WR | P | Zone set or clear |
| Digital operation | 4 | DIFU |  | Take differential up of the node status to operand |
|  | 5 | DIFD |  | Take differential down of the node status too operand |
|  | 10 | TOGG |  | Toggle the coil status |
|  | 11 | (+) | DP | $\mathrm{Sa}+\mathrm{Sb} \rightarrow \mathrm{D}$ |
|  | 12 | (-) | DP | Sa-Sb $\rightarrow$ D |
|  | 13 | ( $\times$ ) | DP | $\mathrm{Sa} \times \mathrm{Sb} \rightarrow \mathrm{D}$ |
|  | 14 | (/) | DP | $\mathrm{Sa} / \mathrm{Sb} \rightarrow \mathrm{D}$ |
|  | 15 | (+1) | DP | Add 1 to D |
|  | 16 | (-1) | DP | Subtract 1 from D |
|  | 23 | DIV48 | P | 48 bits integer division $\mathrm{Sa} / \mathrm{Sb} \rightarrow \mathrm{D}$ |
|  | 24 | SUM | DP | Sum of N consecutive registers |
|  | 25 | MEAN | DP | Average of N consecutive registers |
|  | 26 | SQRT | DP | Square root of $S$ |
|  | 27 | NEG | DP | Two's complement of D (Negative number) |
|  | 28 | ABS | DP | Absolute value of D |
|  | 29 | EXT | P | Extend 16 bits into 32 bits |
|  | 30 | PID | P | PID calculation |
|  | 31 | CRC16 | P | CRC16 calculation |
|  | 32 | ADCNV |  | Offset and full scale conversion for analog input |
|  | 33 | LCNV | P | Linear conversion |
|  | 34 | MLC | P | Multiple linear conversion |


| Category | NO. | Instruction | Derivative | Function |
| :---: | :---: | :---: | :---: | :---: |
|  | 200 | $\stackrel{\mathrm{I}}{\mathrm{F}}$ | DP | Integer to floating point number conversion |
|  | 201 | $\mathrm{F} \rightarrow \mathrm{I}$ | DP | Floating point number to integer conversion |
|  | 202 | FADD | P | Addition of floating point number |
|  | 203 | FSUB | P | Subtraction of floating point number |
|  | 204 | FMUL | P | Multiplication of floating point number |
|  | 205 | FDIV | P | Division of floating point number |
|  | 206 | FCMP | P | Comparison of floating point number |
|  | 207 | FZCP | P | Zone comparison of floating point number |
|  | 208 | FSQR | P | Square root of floating point number |
|  | 209 | FSIN | P | SIN trigonometric function |
|  | 210 | FCOS | P | COS trigonometric function |
|  | 211 | FTAN | P | TAN trigonometric function |
|  | 212 | FNEG | P | Change sign of floating point number |
|  | 213 | FABS | P | Absolute value of floating point number |
|  | 214 | FLN | P | Floating point napierian logarithm |
|  | 215 | FEXP | P | Floating point exponential function |
|  | 216 | FLOG | P | Floating point logarithm |
|  | 217 | FPOW | P | Floating point power function |
|  | 218 | FASIN | P | Floating point arc sine function |
|  | 219 | FACOS | P | Floating point arc cosine function |
|  | 220 | FATAN | P | Floating point arc tangent function |
| $\begin{aligned} & \text { 응 } \\ & \frac{0}{0} \\ & \stackrel{\rightharpoonup}{0} \\ & \stackrel{\rightharpoonup}{3} \end{aligned}$ | 18 | AND | DP | Sa AND Sb |
|  | 19 | OR | DP | Sa OR Sb |
|  | 35 | XOR | DP | Sa XOR Sb |
|  | 36 | XNR | DP | Sa XNR Sb |
| Comparison | 17 | CMP | DP | Value Compare |
|  | 37 | ZNCMP | DP | Zone Compare |

(Continue)

| Category | NO. | Instruction | Derivative | Function |
| :---: | :---: | :---: | :---: | :---: |
|  | 8 | MOV | DP | Move S to D |
|  | 9 | MOV/ | DP | Inverse S and move to D |
|  | 40 | BITRD | DP | Move the Bit-N of S to FO |
|  | 41 | BITWR | DP | Write INB input to the Bit-N of D |
|  | 42 | BITMV | DP | Move the Bit-Ns of S to the Bit -Nd of D |
|  | 43 | NBMV | DP | Move the Nibble-Ns of S to the Nibble-Nd of D |
|  | 44 | BYMV | DP | Move the Byte-Ns of S to the Byte-Nd of D |
|  | 45 | XCHG | DP | Exchange Da and Db |
|  | 46 | SWAP | P | Swap the High-Byte of D with the Low-Byte of D |
|  | 47 | UNIT | P | Take Nb0 of N words to form a Word |
|  | 48 | DIST | P | Distribute N Nb of S to NbO of N Words |
|  | 49 | BUNIT | P | Low byte of words re-unit |
|  | 50 | BDIST | P | Words split into multi-byte |
|  | 160 | RW-FR | DP | File register access |
|  | 161 | WR-MP |  | Write memory pack |
|  | 162 | RD-MP | P | Read memory pack |
|  | 6 | BSHF | DP | Shift D right 1 bit or left 1 bit |
|  | 51 | SHFL | DP | Shift D left N bits |
|  | 52 | SHFR | DP | Shift D right N bits |
|  | 53 | ROTL | DP | Rotate D left N bits |
|  | 54 | ROTR | DP | Rotate D right N bits |
| 응 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 | 20 | $\rightarrow \mathrm{BCD}$ | DP | Convert S into BCD |
|  | 21 | $\rightarrow \mathrm{BIN}$ | DP | Convert S into Binary |
|  | 55 | $B \rightarrow G$ | DP | Binary to Gray code conversion |
|  | 56 | $\mathrm{G} \rightarrow \mathrm{B}$ | DP | Gray code to Binary conversion |
|  | 57 | DECOD | P | Decode the Ns ~ NI of S |
|  | 58 | ENCOD | P | Encode the Ns ~ NI of S |
|  | 59 | $\rightarrow$ 7SG | P | Convert N+1' Nb of S into 7-segment code |
|  | 60 | $\rightarrow$ ASC | P | Convert character/number into ASCII code |
|  | 61 | $\rightarrow$ SEC | P | Convert hour, minute, second by seconds |
|  | 62 | $\rightarrow$ HMS | P | Convert second by hour, minute and second |
|  | 63 | $\rightarrow$ HEX | P | Convert ASCII code into hexadecimal |
|  | 64 | $\rightarrow$ ASCII | P | Convert hexadecimal into ASCII code |
|  | 0 | MC |  | Master control loop start |
|  | 1 | MCE |  | Master control loop end |
|  | 2 | SKP |  | The start of the skip loop |
|  | 3 | SKPE |  | The end of the skip loop |
|  |  | END |  | Terminate the execution of program (for debugging) |
|  | 22 | BREAK | P | Exit from FOR-NEXT Ioop |
|  | 65 | LBL |  | Define the string as label |
|  | 66 | JMP | P | Jump instruction |
|  | 67 | CALL | P | Call instruction |
|  | 68 | RTS |  | Subroutine return instruction |
|  | 69 | RTI |  | Interrupt return instruction |
|  | 70 | FOR |  | The start of the FOR loop |
|  | 71 | NEXT |  | Return point of FOR loop |
|  | 74 | IMDIO | P | Refresh I/O immediately |
|  | 76 | TKEY | D | 10 keys input convenient instruction |
|  | 77 | HKEY | D | 16 keys input convenient instruction |
|  | 78 | DSW | D | Thumbwheel switch input convenient instruction |
|  | 79 | 7SGDL | D | 7 -segment multiplexing display convenient Instruction |
|  | 80 | MUXI |  | Multiplexing input convenient instruction |
|  | 81 | PLSO | D | Pulse output(PSO) instruction |
|  | 82 | PWM |  | Pulse Width Modulation (PWM) output instruction |
|  | 83 | SPD |  | Pulse speed detection instruction |
|  | 84 | TDSP |  | 7/16-segment LED display control |
|  | 86 | TPCTL |  | PID temperature control |
|  | 139 | HSPWM |  | High speed PWM pulse output |


| Category | NO. | Instruction | Derivative | Function |
| :---: | :---: | :---: | :---: | :---: |
|  | 87 | T. 01 S |  | 0.01 S time base accumulative timer |
|  | 88 | T.1s |  | 0.15 time base accumulative timer |
|  | 89 | T1S |  | 1S time base accumulative timer |
| Monitor and control | 90 | WDT | P | Set watchdog timer |
|  | 91 | RSWDT | P | Reset watchdog timer |
| HSC/HST | 92 | HSCTR | P | Read CV of hardware high speed counter/timer |
|  | 93 | HSCTW | P | Write CV or PV of hardware high speed counter/timer |
| Text | 94 | ASCWR |  | Output ASCII message |
| Ascend/ Descend | 95 | RAMP |  | Ascending/Descending convenient instruction |
|  | 98 | RAMP2 |  | Tracking type RAMP function for D/A output |
| Communication | 150 | M-BUS |  | Modbus protocol communication |
|  | 151 | CLINK |  | Fatek CPU link/Generic protocol communication |
|  | 100 | $\mathrm{R} \rightarrow \mathrm{T}$ | DP | Move register Rs to the table Td |
|  | 101 | $T \rightarrow R$ | DP | Move the Rp of table Ts to register Rd |
|  | 102 | $\mathrm{T} \rightarrow \mathrm{T}$ | DP | Move the Rp of table Ts to the Rp of table Td |
|  | 103 | BT_M | DP | Move table Ts to table Td |
|  | 104 | T_SWP | DP | Swap Ta and Tb |
|  | 105 | R-T_S | DP | Search Rs from table Ts |
|  | 106 | T-T_C | DP | Compare table Ta and table Tb |
|  | 107 | T_FIL | DP | Fill Rs into Td table |
|  | 108 | T_SHF | DP | Shift table left or right |
|  | 109 | T_ROT | DP | Rotate table left or right |
|  | 110 | QUEUE | DP | First in first out (Queue) instruction |
|  | 111 | STACK | DP | First in last out (Stack) instruction |
|  | 112 | BKCMP | DP | Compare Rs with zone defined by two tables |
|  | 113 | SORT | DP | Sort the table |
|  | 120 | MAND | P | AND two matrixes |
|  | 121 | MOR | P | OR two matrixes |
|  | 122 | MXOR | P | Exclusive OR (XOR) two matrixes |
|  | 123 | MXNR | P | Exclusive NOR (XNR) two matrixes |
|  | 124 | MINV | P | Inverse matrix |
|  | 125 | MCMP | P | Compare two matrixes and find out the differences between two matrixes |
|  | 126 | MBRD | P | Read the bit of a matrix pointed by pointer |
|  | 127 | MBWR | P | Write the bit of a matrix pointed by pointer |
|  | 128 | MBSHF | P | Shift matrix left 1 bit or right 1 bit |
|  | 129 | MBROT | P | Rotate matrix left 1 bit or right 1 bit |
|  | 130 | MBCNT | P | Count the number of bit whose value is 1 or 0 in the matrix |
|  | 140 | HSPSO |  | High-speed pulse output |
|  | 141 | MPARA |  | Set NC position parameters |
|  | 142 | PSOFF | P | Force to stop pulse output |
|  | 143 | PSCNV | P | Convert pulse count into mechanical value for display |
|  | 147 | MHSPO |  | Multi-Axis high speed pulse output |
|  | 148 | MPG |  | Manual pulse generator for positioning |
| Interrupt control | 145 | EN | P | Enable external input or peripheral interrupt |
|  | 146 | DIS | P | Disable external input or peripheral interrupt |
|  | 170 | = | D | Equal to compare |
|  | 171 | > | D | Greater than compare |
|  | 172 | < | D | Less than compare |
|  | 173 | <> | D | Not equal to compare |
|  | 174 | >= | D | Greater than or equal to compare |
|  | 175 | =< | D | Less than or equal to compare |
| Other | 190 | STAT |  | Read system status |

## Dimensions

Figure 1


| W | Model |
| :---: | :--- |
| 90 mm | FBs-20M $\triangle, F B s-24 M \triangle, F B s-24 X Y$ <br> FBs-16TC,FBs-16RTD |
| 130 mm | FBs-32M $\triangle, F B s-40 M \triangle, F B s-40 X Y$ |
| 175 mm | FBs-44MN $\triangle, F B s-60 M \triangle, F B s-60 X Y$ <br> FBs-30GM |

Figure 2


Figure 4


Figure 3


Figure 5


Figure 6


Figure 7


Figure 8


Figure 9


| Module Name |  |  | Specifications |
| :---: | :---: | :---: | :---: |
|  | Basic <br> Main Units | FBs-10MA $\triangle \triangle-\bigcirc-C$ | 6 points 24 VDC digital input ( 4 points medium speed 20KHz, 2 points medium speed total 5 KHz ); 4 points relay or transistor output ( 4 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3 ); I/0 is not expandable |
|  |  | FBs-14MA $>\triangle-$ - - C | 8 points 24 VDC digital input ( 4 points medium speed $20 \mathrm{KHz}, 4$ points medium speed total 5 KHz ); 6 points relay or transistor output ( 6 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3 ); I/0 is not expandable |
|  |  | FBs-20MA $\triangle \triangle-\bigcirc-C$ | 12 points 24 VDC digital input ( 6 points medium speed $20 \mathrm{KHz}, 6$ points medium speed total 5 KHz ); 8 points relay or transistor output ( 8 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3) |
|  |  | FBs-24MA $>\triangle-\bigcirc-\mathrm{C}$ | 14 points 24 VDC digital input ( 8 points medium speed $20 \mathrm{KHz}, 6$ points medium speed total 5 KHz ); 10 points relay or transistor output ( 8 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3) |
|  |  | $\begin{aligned} & \text { FBs-32MA } \diamond \triangle-\text { - }-\mathrm{C} \\ & \text { FBs-32MB } \diamond \triangle-\text { - }-\mathrm{C} \end{aligned}$ | 20 points 24VDC digital input (8 points medium speed 20KHz, 8 points medium speed total 5 KHz ); 12 points relay or transistor output (8 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3); (MB is detachable terminal block) |
|  |  | $\begin{aligned} & \text { FBs-40MA } \diamond \triangle-\text { - }-\mathrm{C} \\ & \text { FBs-40MB } \diamond \triangle-\text { - }-\mathrm{C} \end{aligned}$ | 24 points 24VDC digital input (8 points medium speed 20KHz, 8 points medium speed total 5 KHz ); 16 points relay or transistor output (8 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3); (MB is detachable terminal block) |
|  |  | $\begin{aligned} & \text { FBs-60MA } \diamond \triangle-\text { - }-\mathrm{C} \\ & \text { FBs-60MB } \diamond \triangle-(-)-C \end{aligned}$ | 36 points 24VDC digital input (8 points medium speed 20KHz, 8 points medium speed total 5 KHz ); 24 points relay or transistor output ( 8 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 3); (MB is detachable terminal block) |
|  | Advanced Main Units | FBs-10MC $>\Delta$ - 0 | 6 points 24 VDC digital input ( 2 points high speed 200 KHz , 2 points medium speed $20 \mathrm{KHz}, 2$ points medium speed total 5 KHz ); 4 points relay or transistor output (2 points high speed 200KHz, 2 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; I/ 0 is not expandable |
|  |  | FBs-14MC $>\triangle$ - 0 | 8 points 24VDC digital input (2 points high speed 200KHz, 2 points medium speed $20 \mathrm{KHz}, 4$ points medium speed total 5 KHz ); 6 points relay or transistor output (2 points high speed 200KHz, 4 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; I/ 0 is not expandable |
|  |  | FBs-20MC $\diamond \triangle$ - © | 12 points 24 VDC digital input ( 4 points high speed 200KHz, 2 points medium speed 20 KHz , 6 points medium speed total 5 KHz ); 8 points relay or transistor output (4 points high speed 200KHz, 4 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-24MC $>\triangle$ - 0 | 14 points 24 VDC digital input ( 4 points high speed 200KHz, 4 points medium speed 20 KHz , 6 points medium speed total 5 KHz ); 10 points relay or transistor output (4 points high speed 200KHz, 4 points medium sped 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-32MC $>\triangle$ - © | 20 points 24VDC digital input ( 6 points high speed 200KHz, 2 points medium speed 20KHz, 8 points medium speed total 5 KHz ); 12 points relay or transistor output ( 6 points high speed 200KHz, 2 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-40MC $>\triangle$ - © | 24 points 24 VDC digital input ( 6 points high speed 200 KHz , 2 points medium speed $20 \mathrm{KHz}, 8$ points medium speed total 5 KHz ); 16 points relay or transistor output ( 6 points high speed 200KHz, 2 points medium speed 20KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-60MC $>\triangle$ - 0 | 36 points 24VDC digital input ( 8 points high speed 200KHz, 8 points medium speed total 5 KHz ); 24 points relay or transistor output ( 8 points high speed 200KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  | NC Positioning Main Units | FBs-20MN $>\triangle$ - 0 | 2 sets ( 1 axis) 920 KHz 5 VDC digital differential input, 10 points 24VDC digital input ( 4 points high speed 200KHz, 6 points medium speed total 5KHz); 2 sets ( 1 axis) 920KHz 5VDC digital differential output, 6 points relay or transistor output (average high speed 200KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-32MN $\gg-$ - | 4 sets ( 2 axes) 920KHz 5VDC digital differential input, 16 points 24VDC digital input (4 points high speed 200KHz, 8 points medium speed total 5 KHz ); 4 sets ( 2 axes) 920KHz 5VDC digital differential output, 8 points relay or transistor output ( 4 points high speed 200KHz); 1 RS232 or USB port (expandable up to 5); built-in RTC; detachable terminal block |
|  |  | FBs-44MN $>\triangle$ - 0 | 8 sets ( 4 axes) 920 KHz 5 VDC digital differential input, 20 points 24 VDC digital input ( 8 points medium speed total 5 KHz ); 8 sets ( 4 axes) 920 KHz 5 VDC digital differential output, 8 points relay or low speed transistor output; 1 RS232 or USB port (expandable up to 5 ); built-in RTC; detachable terminal block |
|  | Expansion Power Supply | FBs-EPW-AC/D24 | Power supply of 100~240VAC or 24VDC input for expansion module; 3 sets output power with 5VDC, 24VDC, and 24VDC, 14W capacity |
|  | DIO <br> Expansion Units | FBs-24XY $\diamond$ - 0 | 14 points 24VDC digital input, 10 points relay or transistor output, built-in power supply |
|  |  | FBs-40XY $\diamond$ - 0 | 24 points 24VDC digital input, 16 points relay or transistor output, built-in power supply |
|  |  | FBs-60XY $\diamond$ - 0 | 36 points 24VDC digital input, 24 points relay or transistor output, built-in power supply |
|  | DIO Expansion Modules | FBs-8X | 8 points 24 VDC digital input |
|  |  | FBs-8Y $\diamond$ | 8 points relay or transistor output |
|  |  | FBs-8XY $\diamond$ | 4 points 24VDC digital input, 4 points relay or transistor output |
|  |  | FBs-16Y $\diamond$ | 16 points relay or transistor output |
|  |  | FBs-16XY $\diamond$ | 8 points 24VDC digital input, 8 points relay or transistor output |
|  |  | FBs-20X | 20 points 24VDC digital input |
|  |  | FBs-24XY $\diamond$ | 14 points 24VDC digital input, 10 points relay or transistor output |
|  |  | FBs-40xY $\diamond$ | 24 points 24VDC digital input, 16 points relay or transistor output |
|  |  | FBs-60XY $\diamond$ | 36 points 24VDD digital input, 24 points relay or transistor output |
|  |  | FBs-24X | 24 points high-density 24VDC digital input, 30 pins header with latch |
|  |  | FBs-24YT/J | 24 points high-density transistor SINK(T) or SOURCE(J) output (0.1A max.), 30 pins header with latch |
|  | Thumbwheel Switch Module | FBs-32DGI | 8 sets 4 digits (total 32 digits) thumbwheel switch (or 128 points independent switch) multiplex input module, 30 pins header connector |
|  | 16/7 Segment LED Display | FBs-7SG1 | 1 set 8 digits 7 -segment/4 digits 16 -segment LED display (or 64 points independent LED) output display module, 16 pins header connector |
|  | Modules | FBs-7SG2 | 2 sets 8 digits 7 -segment/4 digits 16-segment LED display (or 128 points independent LED) output display module, 16 pins header connector |
|  | AIO Modules | FBs-2DA | 2 channels, 14-bit analog output module (-10~10V, 0~10V or -20~20mA, $0 \sim 20 \mathrm{~mA}$ ) |
|  |  | FBs-4DA | 4 channels, 14-bit analog output module (-10~10V, 0~10V or -20~20mA, $0 \sim 20 \mathrm{~mA}$ ) |
|  |  | FBs-4A2D | 4 channels, 14-bit analog input (same specification as 6AD) +2 channels, 14-bit analog output (same specification as 2DA) combo module |
|  |  | FBs-6AD | 6 channels, 14-bit analog input module (-10~10V, 0~10V or -20~20mA, 0~20mA) |
|  | Temperature Measurement Modules | FBs-2TC | 2 channels, thermocouple temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |
|  |  | FBs-6TC | 6 channels, thermocouple temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |
|  |  | FBs-16TC | 16 channels, thermocouple temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |
|  |  | FBs-6RTD | 6 channels, RTD temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |
|  |  | FBs-16RTD | 16 channels, RTD temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |
|  |  | FBs-6NTC | 6 channels, NTC temperature input module with $0.1^{\circ} \mathrm{C}$ resolution. |

(Continue)

| Module Name |  |  | Specifications |
| :---: | :---: | :---: | :---: |
|  | AI + Temperature Measurement Combo Modules | FBs-2A4TC | 2 channels, 14-bit analog input (same specifications as 6AD) +4 channels thermocouple temperature input (same specifications as 6TC) combo module |
|  |  | FBs-2A4RTD | 2 channels, 14 -bit analog input (same specifications as 6AD) +4 channels RTD temperature input (same specifications as 6RTD) combo module |
|  | Voice Modules | FBs-VOM | Built-in 1MB memory (play continuously up to 2 minutes), extendable 4GB SD card(play continuously up to 8,000 minutes) voice module, 245 messages, output 2 W |
|  | Load Cell Module | FBs-1LC | 1 channel, load cell measurement module with 16-bit resolution (including sign bit) |
|  | Potential Meter Module | FBs-4PT | 4 channels, 14-bit potential meter input module (Impedance range: 1~10K $\Omega$ ) |
|  | Communication Modules | FBs-CM22 | 2 ports RS232 (Port3 + Port 4) communication module |
|  |  | FBs-CM55 | 2 ports RS485 (Port3 + Port 4) communication module |
|  |  | FBs-CM25 | 1 port RS232 (Port3) + 1 port RS485 (port 4) communication module |
|  |  | FBs-CM25E | 1 port RS232 (Port3) + 1 port RS485 (port 4) + Ethernet network interface communication module |
|  |  | FBs-CM55E | 1 port RS485 (Port3) + 1 port RS485 (port 4) + Ethernet network interface communication module |
|  |  | FBs-CMZB | ZigBee communication module |
|  |  | FBs-CMZBR | ZigBee communication repeater |
|  |  | FBs-CMGSM | GSM wireless communication module |
|  |  | FBs-CM25C | General purpose RS232 to RS485/RS422 communication interface converter with photocouple isolation |
|  |  | FBs-CM5R | General purpose RS485 repeater with photocouple isolation |
|  |  | FBs-CM5H | General purpose 4 ports RS485 HUB with photocouple isolation, RS485 can be connected as star connection |
|  | Communication Boards | FBs-CB2 | 1 port RS232 (Port 2) communication board |
|  |  | FBs-CB22 | 2 ports RS232 (Port 1+ Port 2) communication board |
|  |  | FBs-CB5 | 1 port RS485 (Port 2) communication board |
|  |  | FBs-CB55 | 2 ports RS485 (Port 1+ Port 2) communication board |
|  |  | FBs-CB25 | 1 port RS232 (Port 1) + 1 port RS485 (Port 2) communication board |
|  |  | FBs-CBE | 1 port 10 Base T Ethernet communication board |
|  |  | FBs-CBEH | 1 port 100 Base T Ethernet communication board |
|  |  | FBs-CBCAN | 1 port CANopen communication board |
|  | AIO Boards | FBs-B2DA | 2 channels, 12-bit analog output board (0~10V or 0~20mA) |
|  |  | FBs-B2A1D | 2 channels, 12-bit analog input + 1 channel, 12-bit analog output combo analog board ( $0 \sim 10 \mathrm{~V}$ or $0 \sim 20 \mathrm{~mA}$ ) |
|  |  | FBs-B4AD | 4 channels, 12-bit analog input board (0~10V or 0~20mA) |
|  | Precision Load Cell Module | FBs-1HLC | 1 channel, high precision weighing control module with 24-bit resolution |
|  | 3-Axis Motion Control Module | FBs-30GM | 3-Axis with linear and circular interpolation advanced motional control module, 3 sets of 200 KHz high speed pulse input, 3 sets of 500 KHz high speed pulse output, 14 points main unit, 16M Bytes program capacity, 20K Words retentive file register, built-in RS485 and Ethernet, 7.62 mm detachable terminal block |
|  | Simple HMI | FBs-BDAP | Board type Data Access Panel |
|  |  | FBs-BPEP | Board type Parameter Entry Panel |
|  |  | FBs-PEP/PEPR | Multi characters with graphics-based Parameter Entry Panel, built-in RFID Read/Write module with PEPR |
|  |  | FBs-DAP-B/BR | $16 \times 2$ LCD character display, 20 keys keyboard, 24VDC power supply, RS485 comm. port, built-in RFID Read/Write module with BR |
|  |  | FBs-DAP-C/CR | $16 \times 2$ LCD character display, 20 keys keyboard, 5VDC power supply, RS232 comm. port, built-in RFID Read/Write module with CR |
|  | RFID Card | CARD-H | Read / Write wireless card (for FBs-DAP-BR/CR and FBs-PEPR) |
|  | Programming Devices | FP-08 | FBs- Series PLC handheld programmer |
|  |  | Winproladder | FATEK-PLC Winproladder Programming software |
|  | Memory Pack | FBS-PACK | FBs-PLC program memory pack with 20K Words program, 20K Words register, write protection switch |
|  | PWMDA Module | PWMDA | 10-bit single channel pulse width modulation(PWM) 0~10V analog output (AO) module |
|  | USB- RS232 Converter Cable | FBs-U2C-MD-180 | Communication converter cable with standard USB AM connector to RS232 MD4M connector (used in standard PC USB to FBs main unit Port 0 RS232), length 180 cm |
|  | Communication Cables | FBs-232P0-9F-150 | MD4M to DB9F communication cable (FBs main unit Port 0 RS232 connect to standard DB9M), length 150 cm |
|  |  | FBs-232PO-9M-400 | MD4M to DB9M communication cable (FBs main unit Port 0 RS232 connect to DB9F), length 400 cm |
|  |  | FBS-232PO-MD-200 | MD4M to MD4M communication cable (FBs main unit Port 0 RS232 connect to FBs-PEP/PEPR), length 200 cm |
|  |  | FBs-232P0-MDR-200 | MD4M to 90 ${ }^{\circ} \mathrm{MD4M}$ communication cable (FBs main unit Port 0 RS232 connect to FBs-PEP/PEPR), length 200cm |
|  | High Density DIO Connection Cable | HD30-22AWG-200 | High density modules(FBs-24X, FBs-24YT/J, FBs-32DGI) connector 30pin Socket, 22AWG I/0 cable length200cm |
|  | 16/7-Segment LED Display | DBAN.8-nR | 0.8 " 4-digit 16 -segment LED display, n means R(Red) 16 -segment LED characters display installed, can be 1~4 |
|  |  | DBAN.2.3-nR | 2.3" 4-digit 16 -segment LED display, n means R(Red) 16 -segment LED characters display installed, can be 1~4 |
|  |  | DB.56-nR | 0.56 " 8 -digit 7-segment display, n means R(Red) 7-segment LED characters display installed, can be 1~8 |
|  |  | DB.8-nR | 0.8" 8 -digit 7-segment display, $n$ means $R($ Red $) 7$-segment LED characters display installed, can be 1~8 |
|  |  | DB2.3-nR | 2.3" 8-digit 7-segment display, $n$ means R (Red) 7 -segment LED characters display installed, can be 1~8 |
|  |  | DB4.0-nR | 4.0" 4-digit 7-segment display, $n$ means $R$ (Red) 7 -segment LED characters display installed, can be 1~4 |
|  | Training Box | FBs-TBOX | $46 \mathrm{~cm} \times 32 \mathrm{~cm} \times 16 \mathrm{~cm}$ suitcase, containing FBs-24MCT main unit. FBs-CM25E communication module (RS232 + RS485 + Ethernet network), 14 simulated input switches, 10 external relay output, Doctor terminal outlet I/0, peripherals such as stepping motor, encoder, 7 -segment display, 10 of 10 mm LED indicator, thumbwheel switch, and 16 key keyboard. |

[^0]3. © : AC - 100~240VAC power supply

D12 - 12VDC power supply
D24-24VDC power supply
5. The unmarked frequencies of Digital Input (DI) or Digital Output (DO) are low speed.

##  <br> FATEK ${ }^{\circ}$ automation corporation

26FL., NO. 29, SEC. 2, JUNGJENG E. RD.,
DANSHUEI DIST., NEW TAIPEI CITY 25170, TAIWAN, R.O.C
TEL : +886-2-2808-2192
FAX : +886-2-2809-2618
E-mail : sales@fatek.com tech@fatek.com

Website : www.fatek.com


[^0]:    1. $\diamond: \mathrm{R}$ - Relay output ; T—Transistor SINK(NPN) output J-Transistor SOURCE (PNP) output
    2. $\triangle: 2$ - built-in RS232 port ; U — built-in USB port (non-standard)
